| Printed Pages - 1 |
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Roll No.:

337841(37)

APR-MAY

B. E. (Eighth Semester) Examination, 2020

(New Scheme)

(Mech., Production, Automobile Engg. Branch)

MECHATRONICS

Time Allowed: Three hours

Maximum Marks: 80

Minimum Pass Marks: 28

Note: Attempt all questions. Part (a) of each unit is compulsory. Attempt any two parts from (b), (c) and (d) of each question.

Unit-I rossa (i.metas ng kaj mbhava tummaksantanes niiiliped (Cat

1. (a) Define mechatronics.

2

(b) Explain the areas where mechatronics system can be used.

7

| | (c) | What are the various objectives, advantages and disadvantages of a mechatronics system? | 7 |
|----|-----|--|---|
| | (d) | Explain different types of motion control system used in NC machines. | 7 |
| | | Vasaterna 202 jan kasaling a Unit-H errick complety (v. 3) | |
| 2. | (a) | What is the basic principle of thermocouple? | 2 |
| | (b) | Give an examples for a transducer and state its transduction principle. | 7 |
| | (c) | Write a detailed notes on pressure measuring system. | 7 |
| | (d) | What is Proximity Sensor? Explain the working of an eddy current proximity sensor. | 7 |
| | | Unit-III | |
| 3. | (a) | Name the components used in the hydraulic system. | 2 |
| | (b) | Explain working of a 4/3 position direction control value with sketch of its internal parts. | 7 |
| | (c) | Explain construction and working of an external gear pump with its sketch. | 7 |
| | (d) | Explain construction and working of a Fluid coupling. | 7 |

[3]

Unit-IV

| 4. | (a) | Define control system. | 2 |
|----|-----|--|----|
| | (b) | Describe data acquisition system's basic input/output process with an example. | 7 |
| | (c) | Describe analog to digital and digital to analog conversion. | 7 |
| | (d) | Explain about transient response and frequency response. | 7 |
| | | Unit-V | |
| 5. | (a) | What do you understand by design of mechatronics system? | 2 |
| | (b) | What are the different stages in designing a mechatronics system? | 2 |
| | (c) | Discuss the possible design solutions for CNC lathe. | 7. |
| | (d) | Design a mechatronics system for an electrode arm | |